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GRAPHICAL REPRESENTATION OF GRAIN AND HILLOCK ORIENTATIONS IN ANNEALED A1-1%Si FILMS

D. GERTH and R. A. SCHWARZER

Institut für Metallkunde und Metallphysik der TU, Grosser Bruch 23, D-38678 Clausthal-Zellerfeld, Germany

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The grain-specific texture of Al-1%Si films on oxidized silicon substrates was studied by transmission electron microscopy. Heat treatments at 400 °C and 550 °C gave rise to the sporadic growth of annealing hillocks. Crystal orientations of individual grains and hillocks were determined by means of on-line interpretation of Kikuchi patterns. Many hillock orientations differ from the sharp <111> fibre texture of the layer. The hillocks are assumed to start growing in layer regions where grain orientations deviate from the main <111> fibre texture. Local texture is represented graphically by orientation images using Miller indices, Euler angles, and Rodrigues vectors as orientation parameters.

KEY WORDS Individual grain orientations, orientational mapping, Rodrigues space, TEM, Kikuchi patterns, annealing hillocks, aluminium.

INTRODUCTION

During thermal treatment of thin aluminium films on silicon substrates, hillocks may grow on the surface of the films in order to relax compressive mechanical stress caused by the mismatch of thermal expansion between the metal layer and the substrate. The dependence of hillock growth on deposition and heating temperature, layer thickness, and stress was the subject of many investigations (Pennebaker, 1969; Lahiri, 1970; Bacconier *et al.*, 1988; Chang *et al.*, 1989; Kim, Hummel, 1990; Ericson *et al.*, 1991). A review is given in (d'Heurle, 1989). Several types of hillocks have been reported: hillocks with crystal faces, rounded hillocks, hillocks on top of a single grain, and hillocks located on grain boundaries or triple point junctions. Single as well as polycrystalline hillocks were found.

In some investigations the growth process was studied in-situ in an electron microscope (Zimmermann, 1988; Smith *et al*, 1991; Gerth *et al.*, 1992a). Hillocks tend to grow rapidly above a critical temperature which depends on the film thickness. During further annealing at higher temperatures the hillocks increase in size. They can also coalesce with the underlying grains, and polycrystalline hillocks may recrystallize. The changes of morphology and orientation of the hillocks and adjacent grains during the heating process is one reason for various shapes of hillocks found in some investigations after growth process.

Theoretical studies of hillock growth including computer simulation and comparison with stress relaxation mechanisms were made (Chaudhari, 1974;

Jackson *et al.*, 1982; Bacconier *et al.*, 1988; Sanchez, Arzt, 1992). The main hypothesis is that hillocks grow on grain boundaries or triple point junctions, and that mass transport takes place by grain boundary diffusion (d'Heurle, 1989). The origin and the mechanisms of growth are not well understood yet. Obviously local processes in the region of individual hillocks have to be studied for describing the origin of the hillocks and the mechanisms of mass transport. One important aspect related to these questions is the crystal orientations of the hillock and the neighbouring grains. Because of the anisotropy of stress and the dependence of grain boundary mobility and grain boundary diffusion on the type of the grain boundary, the local misorientation is assumed to play an important role during hillock growth.

Here we present a transmission electron microscope (TEM) study of hillock growth. The crystal orientations of hillocks and grains were determined using the Kikuchi pattern method (Schwarzer, 1990). The findings are illustrated by orientation images of the grain structure.

REPRESENTATION OF LOCAL TEXTURE BY ORIENTATION IMAGES

Description of an Orientation

The crystal orientation is defined by the orientation of the crystal coordinate system $\{C\}$ with respect to a reference coordinate frame $\{S\}$ of the sample (Bunge, 1982). An orientation may be expressed by a rotation matrix g which gives a mathematical description of the formalism to bring one coordinate system in correspondence with the other:

$$\{C\} = \mathbf{g} \cdot \{S\} \tag{1}$$

The sample reference frame $\{S\}$ is rotated into the crystal reference system $\{C\}$. In matrix notation it is:

$$\begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} g_{11} & g_{12} & g_{13} \\ g_{21} & g_{22} & g_{23} \\ g_{31} & g_{32} & g_{33} \end{pmatrix} \cdot \begin{pmatrix} s_1 \\ s_2 \\ s_3 \end{pmatrix}$$
(2)

The components of $\{S\}$ and $\{C\}$ are the three orthogonal basic vectors of the coordinate systems. The matrix **g** can be expressed by using Euler angles, Miller indices, or rotational coordinates. It is possible to transform the different orientation parameters into each other by a comparison of the matrix elements. The formulas are given in (Hansen, 1978; Bunge, 1982). In case of cubic crystal symmetry 24 symmetrically equivalent descriptions \mathbf{g}^e of an orientation exist in a right-handed coordinate system. They are determined by multiplication of one orientation \mathbf{g} by the 24 symmetry elements, \mathbf{g}^c , of the group 432 (Hansen, 1978):

$$\mathbf{g}^e = \mathbf{g}^c \cdot \mathbf{g} \tag{3}$$

If a sample symmetry is considered, further symmetrically equivalent orientations

 \mathbf{g}^{e} are given by the relation:

$$\mathbf{g}^e = \mathbf{g}^c \cdot \mathbf{g} \cdot \mathbf{g}^s \tag{4}$$

where \mathbf{g}^{s} are the symmetry elements of the sample.

The Euler angles describe three rotations which transform the sample reference frame into the crystal frame. The coordinate system is first rotated around the *z*-axis, then around the new *x*-axis, and finally around the new *z*-axis. The three angles of rotation are f_1 , Φ , f_2 . The rotation matrix $g(f_1, \Phi, f_2)$ is then given by (Hansen, 1978; Bunge, 1982):

$$\mathbf{g}(\phi_1 \Phi \phi_2) = \begin{pmatrix} \cos \phi_1 \cos \phi_2 - \sin \phi_1 \sin \phi_2 \cos \Phi \\ -\cos \phi_1 \sin \phi_2 - \sin \phi_1 \cos \phi_2 \cos \Phi \\ \sin \phi_1 \sin \Phi \\ \\ \frac{\sin \phi_1 \cos \phi_2 + \cos \phi_1 \sin \phi_2 \cos \Phi }{-\sin \phi_1 \sin \phi_2 + \cos \phi_1 \cos \phi_2 \cos \Phi } \frac{\sin \phi_2 - \sin \Phi}{\cos \phi_2 - \sin \Phi} \\ -\cos \phi_1 \sin \Phi \\ \end{bmatrix}$$
(5)

In the Euler space three subspaces exist in the given range, as seen in Figure 1 without specific sample symmetry, each of which contains every possible orientation once and only once.

Alternatively the rotation matrix \mathbf{g} can be expressed by using the 6 Miller indices of a reference plane, (hkl), and of a reference direction, [uvw], in this plane. For instance the indices of the sheet plane and the rolling direction are commonly used for the description of texture in sheet metals of cubic crystal



Figure 1 Euler space for cubic crystal and triclinic sample symmetry.

symmetry (Hansen, 1978; Bunge, 1982):

$$\mathbf{g}((hkl)[uvw]) = \begin{pmatrix} \frac{u}{n} & \frac{kw - lv}{mn} & \frac{h}{m} \\ \frac{v}{n} & \frac{lu - hw}{mn} & \frac{k}{m} \\ \frac{w}{n} & \frac{hv - ku}{mn} & \frac{l}{m} \end{pmatrix}$$
(6)

with normalization according to:

$$m = \sqrt{(h^2 + k^2 + l^2)} \qquad n = \sqrt{(u^2 + v^2 + w^2)}$$
(7)

Finally a single rotation axis, specified by its normalized Miller indices, $[t_x t_y t_z]$, and an angle of rotation, **w**, may be used for describing an orientation. The rotation matrix $\mathbf{g}((t_x t_y t_z), \omega)$ has the following form (Hansen, 1978):

$$\mathbf{g}((t_x t_y t_z), \omega) = \begin{pmatrix} (1 - t_x^2) \cos \omega + t_x^2 & t_x t_y (1 - \cos \omega) + t_z \sin \omega \\ t_x t_y (1 - \cos \omega) - t_z \sin \omega & (1 - t_y^2) \cos \omega + t_y^2 \\ t_x t_z (1 - \cos \omega) - t_y \sin \omega & t_y t_z (1 - \cos \omega) + t_x \sin \omega \\ & t_x t_z (1 - \cos \omega) + t_y \sin \omega \\ & t_y t_z (1 - \cos \omega) + t_x \sin \omega \\ & (1 - t_z^2) \cos \omega + t_z^2 \end{pmatrix}$$
(8)

A Rodrigues vector, \mathbf{r} , can be defined (Frank, 1988) from a rotation axis/angle pair by selection of the smallest possible rotation angle, \mathbf{w} , and normalization of



Figure 2 Rodrigues space for cubic crystal and triclinic sample symmetry.

the vector **t** of the rotation axis according to:

$$\mathbf{r} = \mathbf{t} \cdot \tan \, \mathbf{w}/2 \tag{9}$$

In all cases of crystal symmetry the smallest rotation angle is less than 62.8°. The basic Rodrigues vectors define a three-dimensional Rodrigues space. In Figure 2 the Rodrigues space without specific sample symmetry is given. The shortest vectors reaching the surface are found along the axes at tan (45°/2). The shortest radius vector, along the <111> directions reaching the truncating triangles has a length of tan (60°/2). The maximum angle is found at the corners tan (62.8°/2). The rectangular coordinates of the corner are ($\sqrt{2} - 1$, $\sqrt{2} - 1$, $3 - \sqrt{8}$) (Neumann, 1991). If the sample has a specific symmetry, the orientation cell is that section of the truncated cube which is cut out by the orientation triangle of the sample symmetry (Neumann, 1991).

Orientation Images

For a graphical representation of grain orientations, the three orientation parameters may be assigned to three basic colours that are red, green and blue. Each grain in a micrograph may thus be stained by a unique colour which, on the other hand, can be interpreted in terms of orientation parameters by comparison with a colour legend. Finally an orientation image of the sample is obtained which illustrates the morphology of microstructure *and* the orientation distribution of the grains. A computer program was developed for the construction of an orientation image using the measured individual grain orientations and a digitized micrograph of the sample region. A comparison was made between the representations using Miller indices, Euler angles or Rodrigues vectors for orientation parameterization. In all kinds of representation, however, specific disadvantages become apparent. The best representation depends on the given texture and on the physical problem which is considered.

For orientation images using Miller indices, the three corners of the stereographic standard triangle (inverse pole figure) correspond to the basic colours, i.e. the colour triangle is overlaid on the stereographic standard triangle (Inokuti *et al.*, 1987). For visual clarity, however it is convenient to paint the center in dark (rather than white as in the standard colour triangle) and the corners in bright by the following intensity normalization. The proportion of the intensities of the three basic colours I_R , I_G , I_B is:

$$I_{R}: I_{G}: I_{B} = \frac{r}{\sqrt{2-1}}: \frac{\beta}{45^{\circ}} \left(1 - \frac{r}{\sqrt{2}-1}\right): \left(1 - \frac{\beta}{45^{\circ}}\right) \left(1 - \frac{r}{\sqrt{2}-1}\right)$$
(10)

$$r = \sqrt{\left(\frac{m}{o+1}\right)^2 + \left(\frac{n}{o+1} + 1\right)^2}\beta = \arctan\left(\frac{m}{n}\right) \tag{11}$$

m, *n*, *o* are the normalized Miller indices of the considered direction.

In the case of parameterization by Euler angles the three angular parameters f_1 , Φ , f_2 are assigned to the intensities of the three colours according to:

$$I_R: I_G: I_B = \frac{\phi_2}{90^\circ}; \frac{\Phi - 55^\circ}{35^\circ}; \frac{\phi_1}{360^\circ}$$
(12)

Since subspace III of Figure 1 is less distorted than subspaces I and II (van Houtte, 1987), subspace III is used in the following for a transformation of the Euler angles into colours. In the other subspaces, the same colours from subspace III were taken for each equivalent point of orientation.

For orientation images using the Rodrigues space (Dingley *et al.* 1991) the values of the three components of a Rodrigues vector, r_{x} , r_{y} , r_{z} , are transformed into corresponding intensities of the three basic colours according to:

$$I_R: I_G: I_B = \frac{r_y + \sqrt{2} - 1}{\sqrt{2} - 1}: \frac{r_x + \sqrt{2} - 1}{\sqrt{2} - 1}: \frac{r_z + \sqrt{2} - 1}{\sqrt{2} - 1}$$
(13)

Comparison of Orientation Representations

In the following advantages and disadvantages of orientation images will be discussed in more detail. A straightforward graphical representation of crystallographic directions is obtained by using Miller indices. In thin aluminium films on silicon substrates the layer normal is a direction physically preferred by the deposition process as well as by the build-up of stress and strain during heating. Many sputtered or evaporated films are composed of columnar grains which grow in a parallel direction with the layer normal. For a physical interpretation of local texture it is adequate to depict the Miller indices of this reference direction with respect to each grain in an inverse pole figure. Inverse pole figures, however, suffer from a pronounced distortion of the orientation space. The ratio between an area in a. distortion-free ("homochoric") orientation space (Frank, 1988) and in the inverse pole figure is 61% in the standard triangle 001-011-111 (van Houtte, 1987). Furthermore, two inverse pole figures are necessary for the representation of crystal orientations, e.g. one for the Miller indices of the sample surface plane and another one for an arbitrary reference direction in this plane. Hence it is necessary to present two orientation images of the layer for a full description of crystal texture. In each image grains with a direction closely in common (normal or in the layer plane) are represented by similar colours.



Figure 3 Representation of simulated <111> fibre textures by Miller indices showing inverse pole figures. a) fibre axis parallel with layer normal; b) fibre axis tilted by 15° to layer normal.

The full grain orientation may he reconstructed from the two colour images in the following way. From the symmetrically equivalent orientations only those arc used for imaging whose Miller indices of the sample normal direction [hkl] fall in the standard triangle 001-011-111. One of the permutations of the Miller indices $\langle uvw \rangle$ of an orthogonal direction is given in the standard triangle 001-011-111. For a full description of crystal orientation the sign and sequence of the Miller indices [uvw] is determined considering the condition of orthogonality between [hkl] and [uvw]. If this condition is fulfilled for more than one of the permutations of $\langle uvw \rangle$, these solutions arc symmetrically equivalent. An example for the representation by Miller indices is given in Figure 3 by simulated fibre textures (<111> fibre axis). One fibre axis lies in the normal direction of the sample (Figure 3a, left), the other is tilted by 15° around the y-axis of the sample (Figure 3b, right).



Figure 4 Representation of simulated <111> fibre textures by Euler angles (Symmetry cubic-triclinic). The orientation points are projected to their nearest section plane, *a*) fibre axis parallel with layer normal; *b*) fibre axis tilted by 15° to layer normal.

In the Euler space each orientation is present three times, and the orientation space is distorted. The ratio between an area in a distortion-free orientation space and an area in the Euler space is here less than 22.5% (van Houttc, 1987). A fibre texture with the fibre axis in the normal direction of the sample, as found for example in the case of thin sputtered aluminium films (<111> fibre axis), is represented by a straight line, since Φ and f_2 are constant and only f_1 will change, or f_2 is constant and $f_1 = 0$ and only Φ will change. A fibre texture with a fibre axis in an oblique direction to the sample normal, however, is given by a curved line in Euler space. This is demonstrated by Figure 4 for the same simulated <111> fibre textures as in Figure 3. The usual representations by f_2 = constant sections and f_1 = constant sections are given. The f_1 = constant section representation with restriction to subspace III as proposed by (van Houtte, 1987) was used, due to the smallest distortion of the orientation space and the close relation between Euler space and inverse pole figures. Subspace III (cf. Figure 1) is related to the standard triangles 100-110-111 and 010-110-111 (van Houtte, 1987). The inverse pole figure of the normal direction of the sample is obtained by projection of the orientation distribution along the f_1 = constant sections, and a fibre texture with the fibre axis in the sample normal direction (Figure 4a, top) is represented by points in the f_1 = constant sections in Euler space. If the fibre axis is tilted with respect to the layer normal, the individual grain orientations lie on curved lines in the Euler space (Figure 4b). The visual interpretation of orientations in an orientation image is not easily done due to the difficulty in extracting the intensities of the basic colours from a mixed colour. Similar orientations, however, are represented by similar colours.



Figure 5 Representation of simulated <111> fibre textures by Rodrigues vectors (Symmetry cubic-triclinic). The orientation points are projected to their nearest section plane, *a*) fibre axis parallel with layer normal; *b*) fibre axis tilted by 15° to layer normal.

For comparison, the same fibre textures as in Figures 3 and 4 are given in Figure 5 using Rodrigues vectors. The bounding surfaces of the Rodrigues space are planes in all cases of specific symmetry (Frank, 1988; Neumann, 1991). The Rodrigues space is distorted as well. The invariant volume element, however, deviates from the volume element in a distortion-free orientation space by less than a factor of two (Neumann, 1991). The indices of the rotation axis may be negative, so the origins of colour and Rodrigues space are not congruous. In the consequence same rotation axes but different rotation angles, i.e. collinear Rodrigues vectors but different absolute values, are not represented by colours with similar intensities of the basic colours (see also Eq. (13)). All fibre textures are represented by a straight line in Rodrigues space, irrespective of the angle with respect to the layer normal as a reference direction (Figure 5a and 5b). By selecting the smallest rotation angle, however, one may jump from one rotation axis to another. The result is that grains with a similar orientation may then fall on rather different colours ("umklapp effect").

EXPERIMENTAL

Investigations were carried out with 800 nmAl-1%Si layers on thermally oxidized (001) silicon substrates. The thickness of the silicon oxide layer was about 100 nm. The films were sputter deposited at room temperature (RT) at a deposition rate of 10 nm/s.

The samples were annealed under vacuum. Two different heat treatments were applied:

—direct heating to a fixed temperature (400 $^{\circ}$ C or 550 $^{\circ}$ C) with a further anneal for 30 minutes (called isothermal annealing) and

—stepwise heating from RT up to 550 °C in steps of 50 °C and 6 minutes annealing time.

For transmission electron microscopy, samples were prepared by chemical polishing. The back side of a sample was thinned to a hole by dipping the disk in a mixture of HNO_3 and HF (6.5 : 1). The aluminium layer was protected from etching by a droplet of glycerin under a plastic lid.

The morphology and the individual crystal orientations of the grains after annealing were investigated in a TEM at an accelerating voltage of 300 kV (PHILIPS EM 430). The crystal orientations were measured on-line using microbeam Kikuchi patterns (Schwarzcr, 1990). For each type of sample the orientations of all grains in a selected region (about 200 matrix grains and a few hillocks) were determined. Hillock density, however, is low and consequently the number of hillocks found in a thus selected region is not sufficient for meaningful statistics. Hence the orientations of about 20 more hillocks and of their surrounding grains in similar regions were measured in addition. The micrographs of the areas with the measured grains were digitized. From the measured single grain orientations the data of the orientation parameterizations are calculated by a computer program. The results are represented by orientation images of the grain orientations.

RESULTS AND DISCUSSION

Figure 6 shows the grain structure of the annealed samples by electron micrographs. All the films have a columnar structure after annealing at about 200 °C (Gerth *et al.*, 1992b). Grain growth occurs in the temperature range from about 100 °C to the final temperature. Some hillocks are growing during the anneal process. The micrograph of a stepwise heated sample (Figure 6d) contains three hillocks which form dark patches. In the other samples (Figure 6a-6c) hillocks were found, too, but they are not in the range of the micrographs of Figure 6.

The orientation distributions of the grains in the Al-1%Si layers arc given in Figure 7 by inverse pole figures for the plane normal direction and for an arbitrary reference direction in the layer plane. It turns out that the majority of the grains are closely oriented along a <111> fibre texture. There are no preferred crystal directions present in the layer plane. This texture is represented by straight lines in the Rodrigues space (Figure 8) as well as in Euler space along $f_2 = 45^{\circ}$ and $\Phi = 5.73^{\circ}$ (= $\arccos(1/\sqrt{3})$ (Figure 9). On the as-deposited samples a <111> fibre texture was confirmed by x-ray pole figure measurement. Strength of texture is reduced during grain growth at high temperatures. Texture is sharper after stepwise heating up to 550 °C than after isothermal heating at 550 °C.



Figure 6 TEM micrographs of 800 nm Al-1%Si layers annealed on SiO_2/Si substrates at different temperatures.



Figure 7 Inverse pole figures of 800 nm Al-1%Si layers as deposited and annealed on SiO_2/Si substrates. Hillock orientations are indicated by circles.



Figure 8 Orientation image using Rodrigues vectors. Sample: 800 nm Al-1%Si layer on Si substrate after stepwise annealing from RT to 550 °C (Symmetry cubic-triclinic). *a*) colour key; *b*) individual orientations in Rodrigues space; *c*) orientation image.

The orientation distribution of grains adjacent to hillocks is given in Figure 10 by inverse pole figures for the plane normal direction and the arbitrary reference direction in the layer plane. Many grains deviate from the pronounced <111> fibre texture of the layer. In the stepwise heated sample the grains in the neighbourhood of hillocks have a sharper <111> fibre texture than in the isothermally annealed one. After annealing up to 400 °C the hillocks have the same orientations as the underlying grain, but after annealing up to 550 °C some hillocks differ in orientation, as a result of grain growth and hillock recrystallization.

The conclusion is drawn that the hillocks start growing in regions with a local texture deviating from the ordinary <111> fibre texture of the layer. In the beginning the hillocks have the same orientations as the grains beneath. Also polycrystalline hillocks were found. Other investigations (Ericson *et al.*, 1991; Gerth *et al.*, 1992b) support the conclusion that hillocks grow above grain boundaries or triple point junctions. During further heating, the grains beneath may coalesce with neighbouring grains having a <111> orientation while the hillocks retain their initial orientation. Therefore at higher temperatures, hillocks may have an orientation quite different from the underlying grains. Hillocks even above a single grain were found. In these cases grain growth of the underlying grains may have annihilated the grain boundary or the triple point junction beneath the hillock (Gerth *et al.*, 1992a). Hillock recrystallization may also occur (Ericson *et al.*, 1991), and as a result some hillocks with a <111> orientation are formed, particularly at higher temperatures.

As an example the different textures of hillocks and grains are shown in orientation images of the stepwise heated layer in terms of Rodrigues vectors, Euler angles and Miller indices (Figures 8, 9 and 11). The hillock orientations differ from the grain orientations of the layer which is illustrated by colour differences. The clearest plot of this finding is given by Miller indices repre-



Figure 10 Inverse pole figures of grains neighbouring hillocks. Samples: 800 nm Al-1%Si layers annealed on SiO_2/Si substrates at different temperatures. Hillock orientations are indicated by circles.



Figure 9 Orientation image using Euler angles. (Sample as Figure 8). a) colour key; b) individual orientations in Euler space; c) orientation image.



Figure 10 Inverse pole figures of grains neighbouring hillocks. Samples: 800 nm Al-1%Si layers annealed on SiO_2/Si substrates at different temperatures. Hillock orientations are indicated by circles.



reference direction in the layer plane

Figure 11 Orientation image using Miller indices and inverse pole figures (top: normal direction, bottom: reference direction in the layer plane). (Sample as Figure 8). a colour key; b individual orientations; c) orientation images.

sentation: While all matrix grains appear in nearly the same (blue) colour in the normal direction image, the hillocks contrast from the preferred <111> fibre axis of the matrix by striking colours.

CONCLUSION

The measurement of crystal orientations of single grains and hillocks in annealed Al-1%Si layers on oxidized silicon substrates reveals a deviation of the local textures of hillocks and their surrounding grains from the ordinary <111> fibre texture of the layers. A grain-specific distribution of orientations is clearly displayed by orientation images using Miller indices, Euler angles or Rodrigues vectors. In the case of a <111> fibre texture, as in sputter-deposited thin aluminium films on a silicon substrate, the most appropriate orientation image is obtained by using Miller indices for orientation parameterization with one reference direction coincident with the fibre axis.

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Hillocks are concluded to start growing on points with an orientation deviating from the <111> fibre texture of the layer. After heat treatments at higher temperatures the crystal orientations of the hillocks and the underlying grains may change by grain growth and recrystallization processes.

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